Action Recognition & Categories via Spatial-Temporal Features

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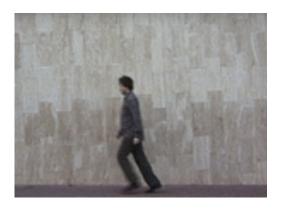
Talk at "Image & Video Analysis" taught by Huimin Yu.

Outline

- Introduction
- Frameworks
 - Feature extraction and description
 - Action Classification
- Multiple actions categories
- Experiments
- Reference

Introduction

 Motivation: How detection and recognition behavior from video sequences?

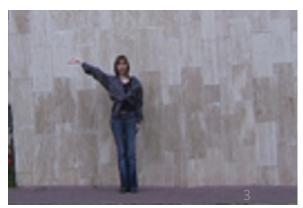












Introduction

 Motivation: How recognize and localize multiple actions in long and complex video sequences containing multiple motions?

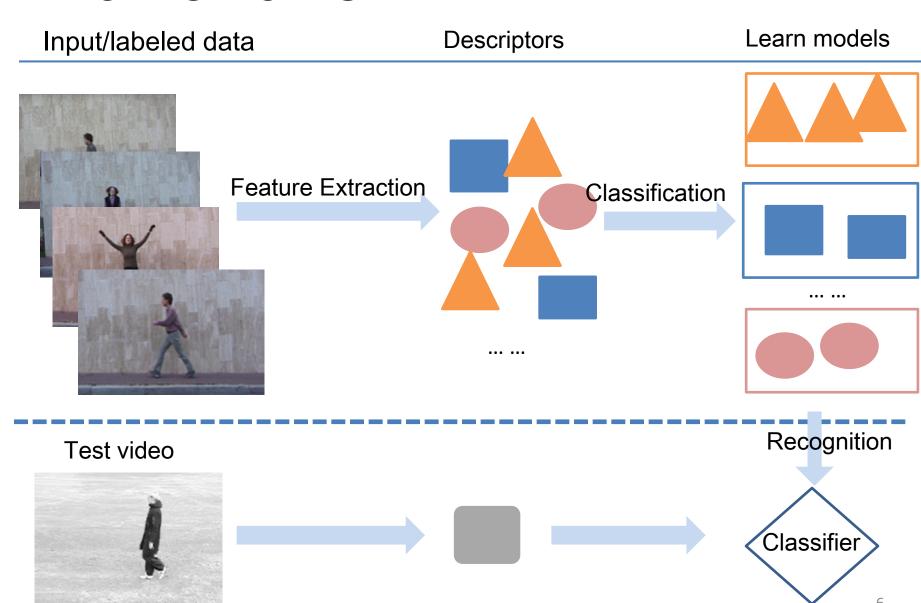




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Frameworks



Feature Extraction

Interest point detection

– Response function:

$$R = (I * g * h_{ev})^{2} + (I * g * h_{od})^{2}$$

where $g(x, y; \sigma)$ is the 2D Gaussian smoothing kernel. And h_{ev} and h_{od} are a quadrature pair of 1D Gabor filters applied temporally.

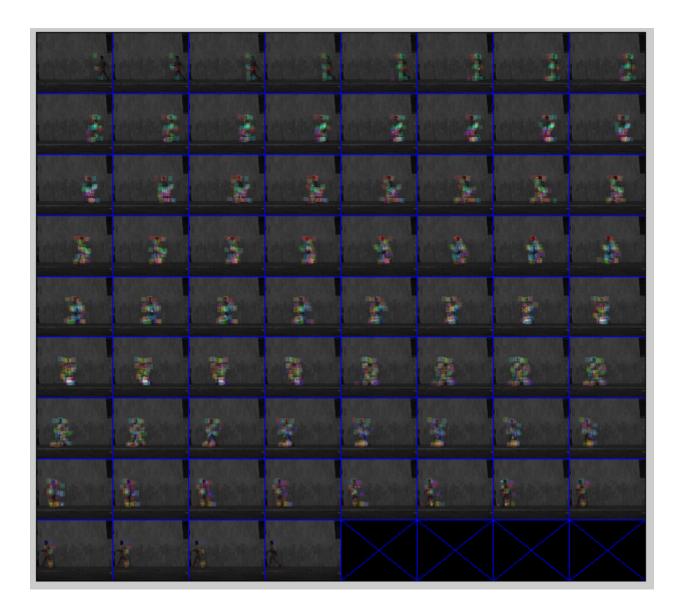
$$h_{od}(t;\tau,\omega) = -\sin(2\pi t\omega)e^{-t^2/\tau^2}$$
$$h_{ev}(t;\tau,\omega) = -\cos(2\pi t\omega)e^{-t^2/\tau^2}$$

Using $\omega = 4/\tau$. the tuning parameters σ and τ are corresponding roughly to the spatial and temporal scale of the detector.

A Cuboid

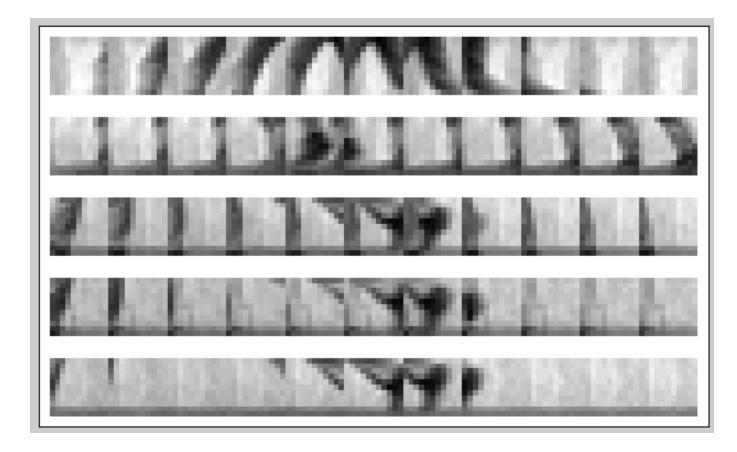
- A cuboid is extracted which contains the spatio-temporally windowed pixel values.
- Size(x, y, t): $(2[3\sigma] + 1, 2[3\sigma] + 1, 2[3\tau] + 1)$

Interest Points visualization



Type: Walk \sigma = 1.5 \tau = 1.5

The Cuboid visualization

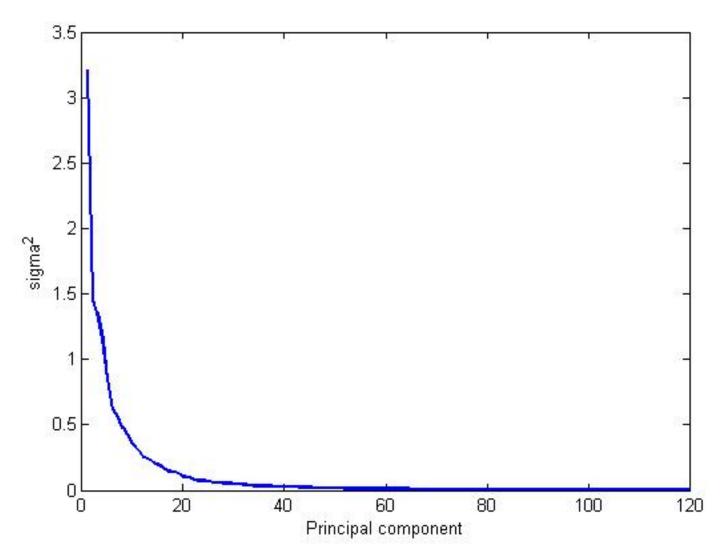


Type: Walk \sigma = 1.5 \tau = 1.5

Feature Extraction(cont.)

- Cuboid to a feature vector
 - Gaussian smoothing (at different scale, \sigma)
 - Calculate the brightness gradient (G_x,G_y,G_t) at each spatio-temporal location (x, y, t)
 - string out vector
- Dimensionality reduction: PCA
 - Random subsample cuboids from all data
 - Calculate the first k principal components by PCA.
 (setting k = 100)
 - Project the centralized feature vectors into the new basis. (N x k)
 - (PCA-SIFT descriptor)

Principal components are descending sorted by the corresponding variances.



Feature Description

Cuboid Prototype

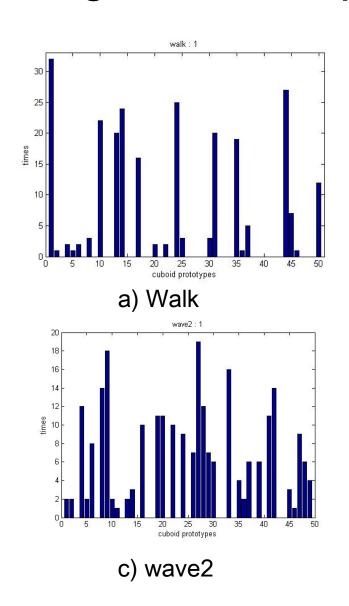
- Create a library of cuboid prototype by clustering the cuboids descriptors.
- Using K-means and Euclidean distance, setting k=50

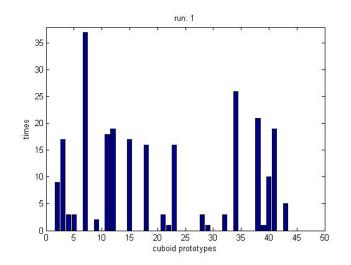
Behavior Descriptor

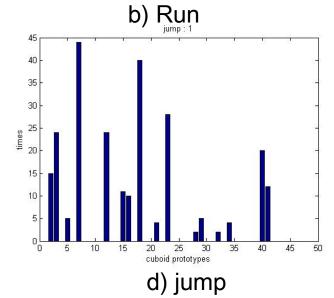
- Use a histogram of the cuboid types as the behavior descriptor.
- Distance between histograms: chi-squared distance

$$d_{\chi^2}(x,y) = \sum_{i} \frac{(x_i - y_i)^2}{2(x_i + y_i)}$$

Histogram Descriptor Samples:







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Classification

- Simplest method: 1-NN
 - Find nearest neighbors based on chi-squared distance.
- Support Vector Machine
 - Use Norm2 SVM (least square SVM)
 - Use chi-squared Kernel

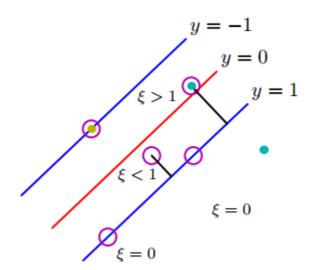
$$K_{\chi^2 - RBF}(x, x') = \exp(-\rho(1 - d_{\chi^2}(x, x')))$$

- Multiclass SVM: one-versus-the-rest
 - appropriate scale
 - Imbalance: Positive class: +1; negative class: -1/(K-1)

A Brief Intro. to SVM

The two-class classification problem: minimize

$$C\sum_{n=1}^{N} \xi_n + \frac{1}{2} \|w\|^2$$



subject to

$$t_n(w^T\phi(x) + b) \ge 1 - \xi_n, n = 1..., N$$

where $t_n \in \{-1,1\}$, $\xi_n \geq 0$ are slack variables. Using Lagrange multipliers, we obtain the dual Lagrangian,

$$\tilde{L}(a) = \sum_{n=1}^{N} a_n - \frac{1}{2} \sum_{n=1}^{N} \sum_{m=1}^{M} a_n a_m t_n t_m k(x_n, x_m)$$

subject to $0 \le a_n \le C$ (box constraints) and $\sum_{n=1}^N a_n t_n = 0$

Optimization methods:

- 1) Quadratic Programming(QP): Chunking(Vapnik, 1982, Burges, 1998)
- 2) Sequential minimal optimization, or SMO (Platt, 1999)

A Brief Intro. to LS-SVM

The classification problem becomes minimizing

$$C\sum_{n=1}^{N}e_{n}^{2}+\frac{1}{2}\|w\|^{2}$$

Lost the sparseness

Define the Lagrangian, and Lagrangian multipliers α_n can be either positive or negative due to KKT conditions. The solution now can be written as the set of linear equation,

$$\begin{bmatrix} I & 0 & 0 & -Z^T \\ 0 & 0 & 0 & -Y^T \\ 0 & 0 & \gamma I & -I \\ \hline Z & Y & I & 0 \end{bmatrix} \begin{bmatrix} w \\ b \\ e \\ \hline \alpha \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \hline \vec{1} \end{bmatrix}$$
(19)

where $Z = [\varphi(x_1)^T y_1; ...; \varphi(x_N)^T y_N], Y = [y_1; ...; y_N], \vec{1} = [1; ...; 1], e = [e_1; ...; e_N],$ $\alpha = [\alpha_1; ...; \alpha_N].$ The solution is also given by

$$\left[\begin{array}{c|c}
0 & -Y^T \\
\hline
Y & ZZ^T + \gamma^{-1}I
\end{array}\right] \left[\begin{array}{c}
b \\
\hline
\alpha
\end{array}\right] = \left[\begin{array}{c}
0 \\
\hline
\vec{1}
\end{array}\right].$$
(20)

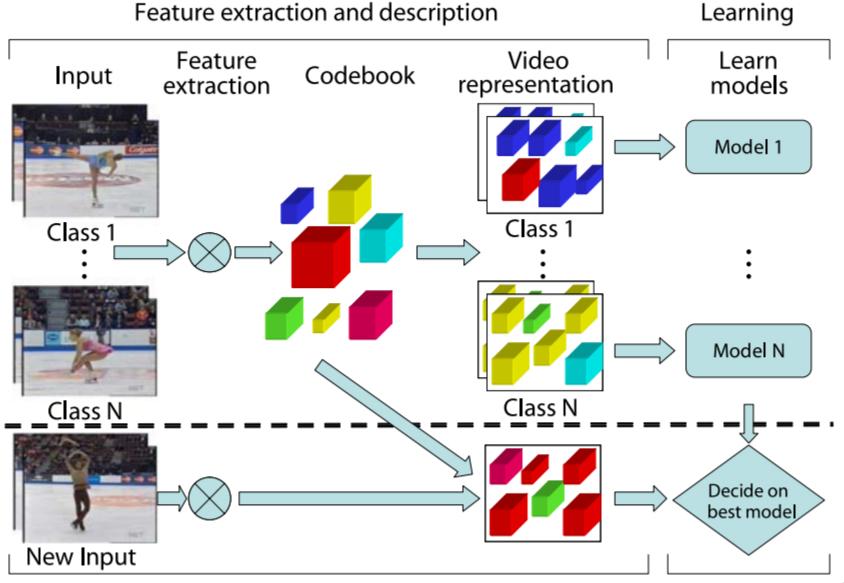
Mercer's condition can be applied again to the matrix $\Omega = ZZ^T$ where

$$\Omega_{kl} = y_k y_l \, \varphi(x_k)^T \varphi(x_l)
= y_k y_l \, \psi(x_k, x_l).$$
(21)

Outline

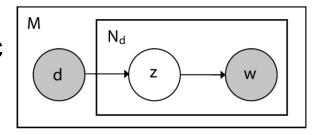
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Multi-actions categories Framework



Multi-actions categories scheme

- Feature Extraction: Cuboid descriptor(PCA-SIFT)
- Build vocabulary(codebook):
 - by clustering using k-means and Euclidean distance, k = 1000
- Label each codeword (w_i) with a topic/category (z_k)
 - Assign each interest point (training) to a codeword
 - By maximizing the posterior P(z_k | w_i)
- Assign detected interest points a topic
 - By assign each point to a codeword
- Topic Localization
 - how many action categories are significantly in a single sequence?
 - k-means to the spatial position of space-times patches.
 - Each word votes for its assigned action within its cluster.



- Topic Localization(cont.)
 - how many action categories are significantly in a single sequence?
 - Tuning parameters.

```
% how many action categories ?
categ_idx = [];
k = 0;
for j=1:ntype
    if type_prob(j)>0.5 ||...
        (type_prob(j)>0.4 && type_cnts(j) > 5) ||...
        (type_prob(j)>0.3 && type_cnts(j) > 14) ||...
        (type_prob(j)>0.2 && type_cnts(j) > 13) ||...
        (type_prob(j)>0.1 && type_cnts(j) > 15)
        categ_idx = [categ_idx,j];
        k = k + 1;
    end
end
```

We call this method Voting.

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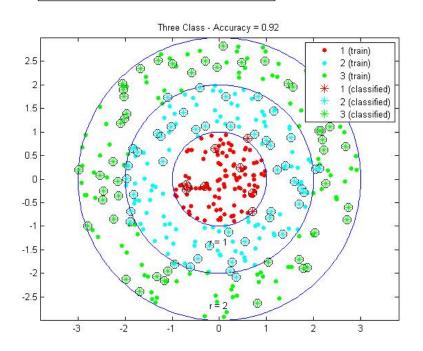
SVM Classifier on Toy dataset

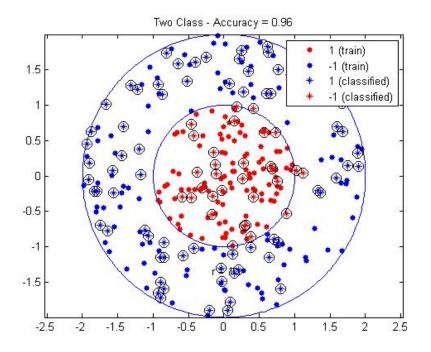
Accuracy:

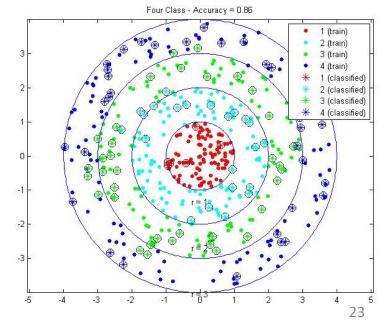
2 class: 0.9600

3 class: 0.9200

4 class: 0.8600







-- X

Experiment 1: Weizmann dataset

- Dataset Setup
 - Weizmann human action dataset [1]
 - Contains 90 low-resolution (180x144,50fps) video sequences showing 9 different people, each performing 10 actions (bend, jack, jump, pjump, run, side, skip, walk, wave1,wave2)



jack jump run [1] http://www.wisdom.weizmann.ac.il/~vision/SpaceTimeActions.html

Result: Weizmann by 1NN

- \sigma = 1.2, \tau = 1.2,
- maxn(interest points) = 200
- Kpca = 100
- Divide into 9 subset
- Leave-one-out test
- Repeat: 5 times
- Overall accuracy: 0.7933

		is .								1.5
bend	1.0	.00	.00	.00	.00	.00	.00	.00	.00	.00
jack	.00	1.0	.00	.00	.00	.00	.00	.00	.00	.00
jump	.00	.00	.71	.00	.04	.00	.24	.00	.00	.00
pjump	.00	.00	.00	1.0	.00	.00	.00	.00	.00	.00
run	.00	.00	.00	.00	.67	.02	.31	.00	.00	.00
side	.00	.00	.02	.00	.04	.87	.02	.04	.00	.00
skip	.00	.00	.33	.00	.29	.00	.29	.09	.00	.00
walk	.00	.00	.04	.00	.00	.04	.11	.80	.00	.00
wave1	.00	.00	.00	.00	.00	.00	.00	.00	.87	.13
wave2	.02	.02	.00	.00	.00	.00	.00	.00	.22	.73
	,							10	2	16



Result: Weizmann by LS-SVM

bend

iack

jump

pjump

run

side

skip

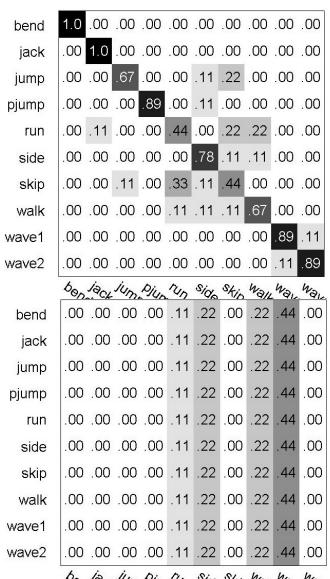
walk

wave1

wave2

wave1

wave2



Linear: 0.7467

RBF:

0.1000

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polack inubling and side skip walk ware a

Polynomial: 0.7556

.67 .11 .00 .00 .00 .00 .11 .11 .00 bend .67 .00 .00 .00 .00 .00 .00 .00 .22 .11 jack .67 .00 .11 .11 .00 .00 .00 .00 .11 .00 iump .67 .00 .11 .00 .00 .00 .00 .00 .22 .00 pjump .67 .00 .00 .00 .00 .01 .00 .22 .00 run .67 .11 .00 .00 .00 .11 .00 .11 .00 .00 side .67 .00 .00 .00 .00 .00 .11 .11 .11 .00 skip .78 .11 .00 .00 .00 .00 .00 .00 .00 .11 walk

.78 .00 .00 .00 .11 .00 .00 .00 .11 .00

.67 .00 .11 .00 .00 .00 .00 .00 .11 .11

Chi-squared:

0.1022

Result: Weizmann by Voting

- \sigma = 1.2, \tau = 1.2, maxn(interest points) = 200
- Kpca = 100
- ncodeword = 1000
- Divide into 9 subset
- Leave-one-out test
- Repeat: 5 times
- Overall accuracy: 0.7333

	_									100
bend	1.0	.00	.00	.00	.00	.00	.00	.00	.00	.00
jack	.00	1.0	.00	.00	.00	.00	.00	.00	.00	.00
jump	.00	.00	.56	.00	.00	.00	.33	.11	.00	.00
pjump	.00	.00	.00	1.0	.00	.00	.00	.00	.00	.00
run	.00	.00	.11	.00	.67	.00	.22	.00	.00	.00
side	.00	.00	.00	.00	.00	1.0	.00	.00	.00	.00
skip	.00	.00	.67	.00	.22	.00	.11	.00	.00	.00
walk	.00	.00	.00	.00	.00	.00	.00	1.0	.00	.00
wave1	.11	.00	.00	.00	.00	.00	.00	.00	.00	.89
wave2	.00	.00	.00	.00	.00	.00	.00	.00	.00	1.0



Experiments 2: KTH dataset

Dataset setup:

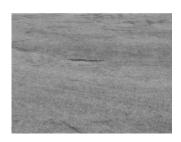
- KTH human action dataset [2]
 - Contains 6 types of human actions (walking, jogging, running, boxing, hand waving and hand clapping) preformed by 25 difference people in 4 different scenarios of outdoor and indoor environment with scale change.
 - Total 598 (160x140) video sequences



boxing



handclapping



jogging



handwaving



running



walking

Great thanks to xcy for downloading the dataset.

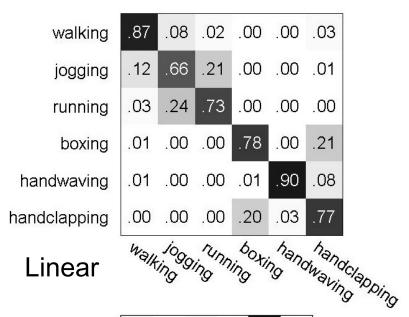
[2] http://www.nada.kth.se/cvap/actions/

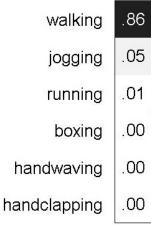
Result: KTH dataset by 1NN

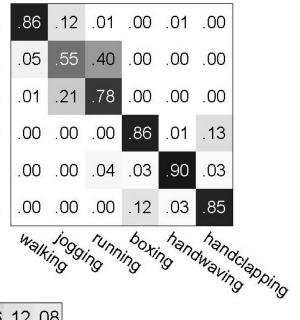
- \sigma = 2, \tau = 2.5,
- maxn(interest points) = 300
- Kpca = 200
- Divide into 25 subsets
- Leave-one-out test
- Repeat: 5 times
- Overall accuracy: 0.8179

	walking	.90	.08	.02	.01	.00	.00
	jogging	.05	.67	.28	.00	.00	.00
	running	.00	.23	.77	.00	.00	.00
	boxing	.01	.00	.00	.84	.00	.15
handwaving		.00	.00	.00	.02	.91	.06
handclapping		.00	.00	.00	.16	.02	.82

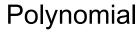
Result: KTH dataset by LS-SVM

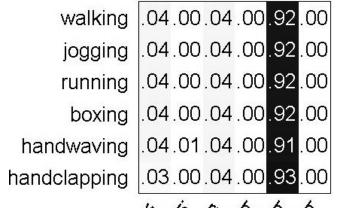


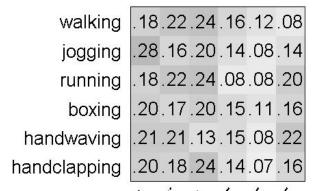




Linear







v

Linear: 0.7844

Polynomial: **0.7996**

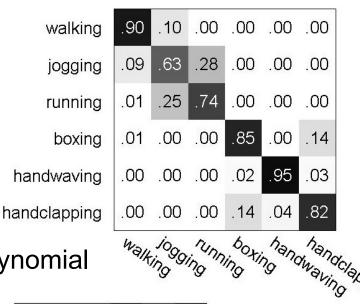
RBF: 0.1656

Chi-squared: 0.1624

Tunbox handandela Chi-squared

Result: KTH dataset by Norm1 SVM

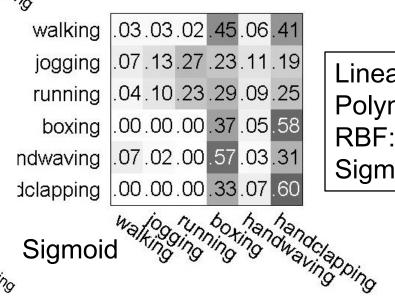




handclapping handwaving. boting Linear

Polynomial





Linear: 0.7429

Polynomial: 0.8146

RBF: 0.1873

Sigmoid: 0.2309

handwaving apping **RBF**

Sigmoid

Result: KTH dataset by Voting

- \sigma = 2, \tau = 2.5, maxn(interest points) = 300
- Kpca = 200
- Ncodeword = 1000
- Divide into 25 subset
- Leave-one-out test
- Repeat: 5 times
- Overall accuracy: 0.9047

	walking	.97	.03	.00	.00	.00	.00
	jogging	.10	.84	.06	.00	.00	.00
.7	running	.02	.21	.77	.00	.00	.00
	boxing	.01	.00	.00	.99	.00	.00
handwaving		.00	.00	.00	.07	.93	.00
handclapping		.00	.00	.00	.07	.00	.93

Walking sing running on handwaving apping

Experiments 3: Multi-Actions

Thanks to Lin**, liu*, wang**









Result by Voting Scheme

 Using the Weizmann dataset for training(\sigma = 1.2, \tau = 1.2)









Result by Voting Scheme(cont.)

 Using the KTH dataset for training(\sigma = 2, \tau = 2.5)









Reference

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Any Question?